**COETC Course Map**

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| **Course Name:** Open ELT 248 Automation Control Circuits |
| **Course Competencies:**  Introduces the fundamentals of automatic controls including process control methodologies used to regulate a  system or multiple systems for the purpose of establishing and maintaining a predictable manufacturing process.   1. Define the term process control. 2. Describe how feedback is used in closed loop process control 3. Define open loop control 4. List the three criteria for evaluating the performance of closed loop control 5. List three key characteristics that determine the response of a system to a supply or demand disturbance 6. Describe the response of a single capacity process to a step change disturbance 7. Define the response of a multiple capacity process to a step change disturbance 8. Explain the relationship between process gain and time constant 9. Describe the inputs and outputs of a two position controller 10. List two advantages and two disadvantages of a two position control 11. Define integral control 12. List one advantage and one disadvantage of integral control 13. Given the equation and the applicable system parameters, calculate the output of an integral controller at some time after a step change in input 14. Define proportional control 15. Describe the relationship between proportional band and gain 16. List one advantage and one disadvantage of proportional control 17. Explain the effect of changing the controller gain on offset error 18. Given the equation and applicable system parameters, calculate the output of a PI controller at some time after a step change input 19. Describe the effect of changing the integral time on the proportional band 20. Describe the effect of changing integral time and proportional band on system stability 21. Define derivative control 22. Given the equation and applicable system parameters, calculate the output of a PD controller at some time during a ramp change input 23. Discuss the effect of changing the proportional band on the derivative action 24. Discuss the effect of changing the proportional band on the proportional action 25. Describe the phase relationship between the proportional, integral and derivative action in a PID controller 26. Given the equation for a PID controller, identify the proportional term the integral term and the derivative term 27. Describe the effect of each mode of a PID controller on stability 28. Explain the difference between feedback control and cascade control 29. Evaluate a control loop and determine if it is a feedback or feed forward control 30. List the major characteristics of feedback, feedforward and cascade control 31. Analyze three element control and describe its use in a control system as compared to one and two element control |

**Course Materials (Text, Edition and any other publisher items)**

**Textbooks and/or Resources:**

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| Practical Process Controls – Tuning and Troubleshooting, by Cecil Smith | | | |
| **Module # and Title** | | **CCNS Competencies** | **Instructional Materials** | **Activities: Learner Interaction & Engagement** | | **Assessments and Rubrics** |
| 1. **Introduction** | | 1 | Module 1 Lecture Outline.html  Module 1 Lecture Slides.pptx |  | | Assignment 1.docx |
| 1. **Process Control Systems** | | 2, 3 | Module 2 Lecture Outline.html  Process Control Terms.pptx  Module 2 Lecture Slides.pptx |  | | Assignment 2.docx Intro to Industrial Controls Quiz.docx |
| 1. **Controller Characteristics** | | 4, 5, 6, 7, 8, 9, 10 | Module 3 Lecture Outline.html  Module 3 Lecture Slides.pptx | ELT 248 Review Activity.htm | |  |
| 1. **Control Theory** | | 11, 12, 13, 14,15, 16, 18, 21, 22, 25, 26, 27 | Module 4 Lecture Outline.html  Module 4 Lecture Slides.pptx |  | | Assignment 3.docx  Module 4 PID Demo Assign.html |
| 1. **Controller Tuning Basics** | | 17, 19, 20, 23, 24, | Module 5 Lecture Slides.pptx |  | | Assignment 4.docx |
| 1. **Motion Control** | | 17, 19, 20, 23, 24, 28 | Module 6 Lecture Outline.html  Module 6 Motion Control.pptx |  | |  |
| 1. **Advanced Control Methods** | | 28, 29, 30, 31 | Module 7 Lecture Slides.pptx |  | | Assignment 5.docx |
| 1. **Designing Automation Control Circuits** | | 27, 31 | Module 8 Designing.html |  | | Final Case Study Assignment.html  Case Study Rubric.html |